Fundamental Open Questions In Distributed Mechanism Design

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Game Theory and Computer Science

Computer science:

- Focus: computational efficiency
- Nodes: obedient or adversarial

Game theory:

- Focus: incentives
- Nodes: selfish

Reality:

- Both computation and incentives matter
- Must look at complexity of economic mechanisms
- Combinatorial auctions are a compelling example

Seminal paper:

- Algorithmic Mechanism Design (AMD) [Nisan-Ronen]
- Most AMD work focuses on *centralized complexity*

<u>This Talk</u>

Considers distributed resource allocation problems

- Users are distributed
- Resources are distributed
- Computation is distributed

Focuses on network complexity

- Assume that the economic mechanism involves a distributed computation carried out over a network
- *Network complexity* measures the computational and communication efficiency of the <u>distributed</u> algorithm

Theme: *distributed algorithmic mechanism design* (DAMD)

Distributed Algorithmic Mechanism Design

Not yet mature:

- No particularly compelling example yet
- Some isolated results, but no coherent framework
- Many fundamental issues unresolved
- Most of these are never even addressed

Purpose of this talk:

- Encourage discussion of these unresolved issues
- Pose both general and specific open questions

<u>Outline</u>

- Review of Mechanism Design Paradigm
- Four Distributed Resource Allocation Problems
- Six Fundamental Questions (long)
- One Final Comment about Canonical Hard Problems

Mechanism Design Paradigm (review)

Resource allocation problem:

- Set of possible allocations or outcomes $\ensuremath{\mathcal{O}}$
- Utilities u_i over \mathcal{O} , $u_i \in \mathcal{U}$
- Social Choice Function (SCF):

 $- F: \mathcal{U}^n \mapsto \mathcal{O}$

• Social Choice Correspondence (SCC):

-
$$H: \mathcal{U}^n \mapsto 2^{\mathcal{O}}$$

Strategyproof SCFs

F is strategyproof if

• $u_i(F(u)) \ge u_i(F(u|^i v_i) \text{ for all } v_i \in \mathcal{U}$

Revelation or direct mechanism:

- No incentive to lie, modulo collusional behavior
- Achieves truthful outcome

Examples:

• VCG mechanisms

Why Not Always Use Strategyproof Direct Mechanisms?

Strategic reason:

- Greatly limits choice of SCF
 - General: Gibbard-Satterthwaite
 - Differentiable: Satterthwaite-Sonnenschein
 - Exchange: Barbera-Jackson
 - Single-peaked: Moulin, Sprumont

- . . .

Practical reasons:

- Communication overhead
- Sometimes agents don't know utility explicitly
 - Probably quite common in network resource cases

(Indirect) Mechanism Design Paradigm

Pick Social Choice Function/Correspondence

Solution concept: C

- C_G describes the selfish outcome in game G
- Models reality, not something you can design

Design mechanism < M, S >

- $M: S^n \mapsto \mathcal{O}$
- Induces game $\langle G, S \rangle$ with $G_i(s) = u_i(M(s))$
- Denote solution concept by $C_M(u)$

Desired Property:

- SCF: $M(C_M(u)) = F(u)$ for all $u \in \mathcal{U}^n$
- SCC: $M(C_M(u)) \subseteq H(u)$ for all $u \in \mathcal{U}^n$

Results:

• With the common solution concepts (*e.g.*, Nash) this approach can implement many nonstrategyproof SCFs

Distributed Resource Allocation Problems

Distributed AMD:

- Considers all distributed resource allocation problems
- The Internet is the biggest and most successful distributed system, making it a natural source of DAMD problems

Four examples (in following slides):

- All Internet-related
- Varying degrees of reality
- Varying degrees of distributed mechanism design

Example #1: Congestion Game

Problem:

- Agent utilities $u_i(r_i, d_i)$
- Delays d function of rates r: d = D(r)
- D represents local packet scheduling algorithm

Results:

- If D=FIFO, Nash is very inefficient (for large n)
- If *D*=FQ, Nash is fair, reasonably efficient

Comment:

• Distributed resources, local (not centralized) mechanism

Example #2: Alternate Path Game

Problem: (simplest form)

- Flows choose from n parallel links
- Congestion on links function of their utilization
- Compare worst-case Nash to social optimal [Koutsoupias-Papadimitriou]

Results: [Roughgarden-Tardos]

 Nash allocation bad, but increasing bandwidth by factor of two offsets selfishness

Comment:

• Distributed resources, but no mechanism

Example #3: Interdomain Routing Game

Problem: [Feigenbaum, Papadimitriou, Sami, S]

- Routing among ASs, currently handled by BGP
- Each AS incurs a cost, and gets paid, for carrying traffic
- Want packets to travel on true lowest-cost paths
- Use VCG pricing scheme so ASs reveal their true costs
- Like shortest-path problem [Nisan-Ronen, H-S] except
 - 1. Nodes (ASs) are strategic entities
 - 2. Consider all source-destination pairs, naively introducing additional n^2 complexity.
 - 3. Distributed BGP-like computational model

Results: (Feigenbaum's talk)

 We can calculate VCG prices without greatly increasing network complexity of BGP

Example #4: Multicast Cost Sharing

Problem:

- Multicast transmission to multiple receivers along a shared delivery tree
- Receivers have utilities u_i for receiving transmission
- Traversing each link l costs c_l
- Mechanism decides which receivers get transmission and how much to charge
- Want a strategyproof pricing mechanism that is budgetbalanced and efficient
- Game-theoretic results: [Moulin, S]
 - Classical result: can't do SP, BB, and Eff
 - Single "best" SP and Eff mechanism: MC (VCG)
 - Single "best" SP and BB mechanism: SH

Results: [Feigenbaum, Krishnamurthy, Papadimitriou, Sami, S]

- MC can be computed in one bottom-up pass followed by one top-down pass of the tree, resulting in each link having at most one message traversal in each direction
- SH can require a linear number of messages crossing at least one link
- MC and SH are two extreme cases:
 - MC is as "easy" as possible
 - SH is as "hard" as possible
- More recent results:
 - Lower bounds on SH apply to a wide class of BB mechanisms (Krishnamurthy's talk)
 - A roughly approximate version of the SH mechanism has low network complexity (Sami's talk)

(Mostly) Common Features

Setting:

- Little information about infrastructure and other players
- Dynamic environment
- Asynchronous

Not standard game-theoretic setting:

- Game theory has treated each of these issues individually, but not jointly
- The confluence is crucial

Computational constraints:

- Communication/computation costs are important
- Mechanisms should have low network complexity

Two Classes of Issues

DAMD raises two different classes of issues:

- Game-theoretic issues in distributed systems
- Distributed computational issues in resulting economic mechanisms

Six Fundamental Questions

- 1. What is the strategic model?
- 2. What is the solution concept?
- 3. Is the selfish outcome sufficiently bad?
- 4. What can be implemented through mechanism design?
- 5. What can be feasibly implemented?
- 6. What can be approximately implemented?

Q1: What is the Strategic Model?

Defining basic aspects:

- Who are the strategic agents?
- How much information do they have?
- Are they collusional or not?
- What can be observed by other agents?
- Is the environment static or dynamic?
- . . .

These are questions about reality, not mathematics:

- Analysis of the problem depends on these assumptions
- Need to make the assumptions explicit

Q2: What is the Solution Concept?

For indirect mechanisms, this is the most basic question:

• What is the result of selfish play?

Answer:

- It depends greatly on the strategic model
- Even given specific strategic model it isn't always clear

Environment:

- Static (and known) infrastructure
- Synchronous play

Standard Solution Concepts:

- One-shot game with common knowledge of G:
 - Rationalizable strategies
 - Nash and refinements thereof

- ...

- Repeated game knowing only own payoff function G_i :
 - Agents learn what strategies to play from history
 - Solution concept is the set of asymptotic plays, which depends on the nature of learning
 - Adaptive: Serially undominated set [Milgrom-Roberts]
 - Calibrated: Correlated equilibria [Foster-Vohra]

— ...

An Internet-like Setting

Environment:

- Prolonged, not one-shot, interactions
- No information about payoff function *G*
 - Even your own payoff function G_i
 - Only know the result of actual play
- Dynamic (and unknowable) infrastructure
- Moderate or extreme asynchrony

Modeling choices:

- Prolonged interaction: repeated game
- Low-information: agents learn what strategies to play
- Dynamic: must adapt to changes in environment
- Asynchrony: agents learn at different speeds

The Corresponding Internet-like Solution Concept:

• No one knows!

Preliminary Work

Several papers: [Friedman, Greenwald, Shor, Sopher, S]

• Theory, simulation, and experiments

Theory:

- Assumed agents use *reasonable* learning algorithms
- Defined minimal criteria for *reasonable* learning
- Derived bounds for the resulting solution concept

Simulations:

- Results consistent with theory
- In this setting, agents don't converge to a small asymptotic set even when using very sophisticated learning algorithms

Preliminary Work (cont'd)

Experiments:

- Human subjects playing for real money
- Convergence sometimes "worse" than in theory
 - Experimentation cascades
- Too early to make sweeping generalizations

Caveat:

- This is just one Internet-like context (but common)
- Applies to several of the examples presented earlier
- But there are many other Internet problems that don't fit this model and to which traditional solution concepts may apply

Open Questions about Solution Concept

General:

• What are the appropriate solution concepts for Internetlike settings?

- Can't just assume Nash is the right solution concept

• Can you design mechanisms to be more "learnable"?

- But must be in the agents' self-interest

Specific:

- If you allow only limited asynchrony, does the solution concept change?
- Can you scalably transform the model from a low-information environment to a high-information one by giving the agents more information?

Q3: Is the Selfish Outcome Sufficiently Bad?

If not, then don't bother with mechanism design!

Previous work:

- Koutsoupias-Papadimitriou formulation:
 - Compare social optimum to worst-case Nash
- Roughgarden-Tardos formulation:
 - Look at increasing resources: Alternate Path Game
 - Degradation in the Nash outcome is offset by doubling the bandwidths
- But the congestion game is different
 - Total Nash utility vanishes in the limit of large n
 - Adding fixed fraction of bandwidth doesn't help

Open Questions about Selfish Outcomes

General:

• Can we characterize the class of problems where increasing the resources by a fixed fraction offsets selfish behavior?

Specific:

• Does the Roughgarden-Tardos result continue to hold with other solution concepts?

Q4: What Can Be Implemented?

Strategyproof direct mechanisms:

• Strategyproofness usually a very restrictive requirement

Indirect mechanisms:

- Depends greatly on the solution concept
- Don't know solution concept for many Internet settings
- For the Internet-like setting and solution concept considered by Friedman *et al.*:
 - Only a subset of strategyproof SCFs are implementable

Strategyproof vs Nonstrategyproof Mechanism Design

Both approaches have significant limitations:

- Strategyproof mechanisms
 - Small subset of SCFs
 - Computational and practical limitations
- Nonstrategyproof (indirect) mechanisms
 - May only implement an even smaller subset of SCFs in some Internet-like settings

Role of nonstrategyproof (indirect) mechanisms:

- Game theory: used to implement a wider set of SCFs
- DAMD: in some Internet-like settings they may only be useful for overcoming computational and practical limitations

Open Questions about Implementation

General:

• What social choice functions and correspondences can be implemented with Internet-like solution concepts?

now leaving pure game theory behind...

Q5: What Can Be Feasibly Implemented?

Three separate feasibility concerns.

- Complexity
- Integrity
- Privacy

Complexity

Must consider both:

- Computational complexity at each node
- Communication complexity (between nodes)

The term *network complexity* refers to both

To evaluate network complexity:

• Need to define computational model of network

Computational Model

Options:

- Traditional TCS computational models (*e.g.*, PODC)
 - It isn't clear how realistic these models are
- Use existing protocols as computational substrate
 - Example: BGP in the interdomain routing game
- Intermediate approach: incorporate certain basic protocol design styles into computational model.
 - Example: soft-state protocols

Open Questions about Complexity

General:

- Which computational models are appropriate for the Internet?
- What mechanisms are computationally feasible with these models?
- Are there reductions, complete problems and, more generally, a complexity theory for Internet computations?

Specific:

- Are there many easy-to-compute VCG mechanisms in the multicast cost sharing problem?
- Does the *revelation principle* still apply?
 - Are there cases where direct mechanism has bad network complexity but an indirect one has good network complexity?
 - Related work on special case [Parkes]

Integrity

The Issue:

 When agents are both the strategic agents <u>and</u> the computational nodes, how can we preserve the integrity of the computation?

One approach: *observability* [Mitchell-Teague]

- Agents observe the protocol actions of neighboring agents
- Agents verify that neighboring agent's actions are consistent with her declared private information
- Extreme punishment for any inconsistency maintains the integrity of the computation

Open Questions about Integrity

General:

- Can we formalize the observability approach?
- Are there other approaches to the Integrity problem?

Specific:

• Does observability constrain the mechanism?

Privacy

The Issue:

• Can we design distributed mechanism-design algorithms such that agents' utilities remain private knowledge?

Observation [Nisan'99]:

 Yes, in theory: Use Secure, Multiparty Function Evaluation (SMFE) developed by crypto community

Problems with generic SMFE protocols:

- Assume large fraction of agents are obedient
- Assume *set* of agents known by all agents
- Require n^2 private channels (information-theoretic model)
- Have unacceptable network complexity

General:

• Are there general approaches to agent privacy in DAMD other than the SMFE approach?

Specific: For specific mechanism-design problems...

- Are there SMFE protocols with low network complexity?
- Are there information-theoretic SMFE protocols that:
 - Don't require the agents to know about, or communicate explicitly with, each other?
 - Don't require n^2 private channels and use the natural network topology for the mechanism?
- Does settling for *partial* privacy of agents' utilities make the problem easier?

Related work:

 [Naor-Pinkas-Sumner], [Monderer-Tennenholtz], [Canetti-Kushilevitz-Ostrovsky-Rosen], [Cramer-Damgaard], [Beaver]

Q6: What Can Be Approximately Implemented?

Approximation may help remove barriers arising from:

• Incentive compatibility

and/or

• Feasibility

Key point:

- Approximating a hard-to-compute mechanism with an easier one is not sufficient
- Must consider the strategic properties of the approximate mechanism

Possible Approaches to Approximation (partial list)

- Loosen strategyproof requirement
 - Approximately strategyproof [Schummer]
 - Feasible dominance [Nisan-Ronen]
 - Tolerable manipulability
- Asymptotic implementation: large number of agents
 - This may not work if agents are *idiosyncratic* and not all resources have many users
 - One approach: [Mehta-Vazirani] Assume agents are idiosyncratically *located* but have *iid* utilities
- Restrict utilities to tractable subset
 - E.g., restricted languages for auctions
- Lotteries: virtual implementation
 - Impressive results for Nash
- Use metric space on outcomes to define approximation

Open Questions about Approximation

General:

• Which approximation approaches are effective?

Specific:

- What can be virtually implemented with strategyproof mechanisms? Other Internet-like solution concepts?
- Which SCCs can you (approximately) achieve knowing the distribution of utilities?
- Do any implementation impossibility results disappear when you allow metric-space approximations?
 - One negative result: Cannot always achieve approximate efficiency and approximate budget-balance with strategyproof mechanisms (Krishnamurthy's talk)

Summary: Distributed Algorithmic Mechanism Design

State of the field:

- Growing consensus that both incentive and computation constraints are important
- Several interesting DAMD problems and results
 - But no single compelling example
 - No coherent framework
- Many fundamental issues unresolved (and unaddressed)

What we need to make progress:

- Work on these unresolved issues (focus of talk) and
- Some canonical hard problems

Canonical Hard Problems

Computer Science:

- Has a collection of canonical hard problems
- Teach us what functions are inherently hard to compute

Game Theory:

- Has a collection of impossibility results
- Teach us what SCFs/SCCs are impossible to implement

Canonical Hard Problems for DAMD

Want distributed allocation problems and an SCC where:

- The computation, ignoring incentives, has low network complexity
- Implementation, ignoring the computational limitations, is possible
- The centralized implementation has low complexity
- <u>But</u> distributed implementations have inherently high network complexity

Such problems teach us about the interaction of incentives and distributed computation

- BB (+ other minor conditions) multicast cost sharing
- We need more!